

Numerical Optimization

Exercise VII

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Quadratic Programming

Equality-constrained case

Minimize $q : \mathbb{R}^n \mapsto \mathbb{R}$,

$$q(\mathbf{x}) := \frac{1}{2} \mathbf{x}^\top \mathbf{G} \mathbf{x} + \mathbf{c}^\top \mathbf{x},$$

subject to $\mathbf{A} \mathbf{x} = \mathbf{b}$, where

$$\mathbf{G} \in \mathbb{R}^{n \times n}, \quad \mathbf{c} \in \mathbb{R}^n, \quad \mathbf{A} \in \mathbb{R}^{m \times n}, \quad \mathbf{b} \in \mathbb{R}^m, \quad m < n,$$

and \mathbf{A} has full row rank.

KKT system:

$$\begin{pmatrix} \mathbf{G} & -\mathbf{A}^\top \\ \mathbf{A} & \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{x} \\ \boldsymbol{\lambda} \end{pmatrix} = \begin{pmatrix} -\mathbf{c} \\ \mathbf{b} \end{pmatrix}$$

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Null space method:

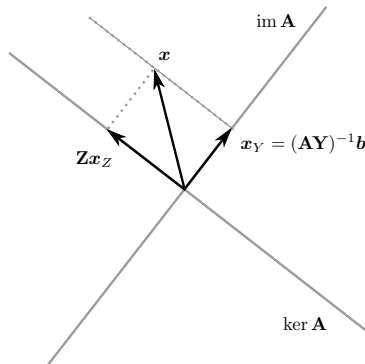
- ▶ distinguish image and null space coordinates of solution:

$$\mathbf{x} = \mathbf{Y}\mathbf{x}_Y + \mathbf{Z}\mathbf{x}_Z$$

- ▶ feasible base point:

$$\mathbf{x}_Y = (\mathbf{A}\mathbf{Y})^{-1}\mathbf{b}$$

(from linear constraint)



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- ▶ Lagrange condition:

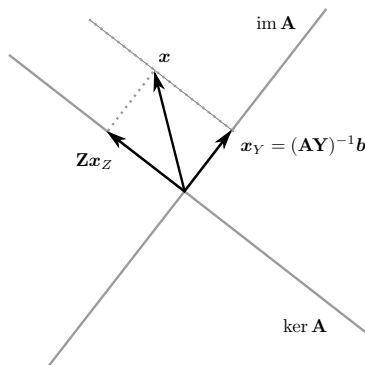
$$\mathbf{GZ}x_Z = \mathbf{A}^\top \lambda - \mathbf{G}y_{x_Y} - c$$

- ▶ after multiplication with \mathbf{Z}^\top :

$$\mathbf{Z}^\top \mathbf{GZ}x_Z = -(\mathbf{Z}^\top \mathbf{G}y_{x_Y} + \mathbf{Z}^\top c)$$

since

$$\mathbf{Z}^\top \mathbf{A}^\top = (\mathbf{AZ})^\top = \mathbf{0}$$



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Other interpretation:

Insert $\mathbf{x} = \mathbf{Y}\mathbf{x}_Y + \mathbf{Z}\mathbf{x}_Z$ into original to obtain *reduced* problem

$$\min_{\mathbf{x}_Z} \frac{1}{2} \mathbf{x}_Z^\top \tilde{\mathbf{G}} \mathbf{x}_Z + \tilde{\mathbf{c}}^\top \mathbf{x}_Z$$

with

$$\tilde{\mathbf{G}} = \mathbf{Z}^\top \mathbf{G} \mathbf{Z} \quad \text{and} \quad \tilde{\mathbf{c}} = \mathbf{Z}^\top \mathbf{G} \mathbf{Y} \mathbf{x}_Y + \mathbf{Z}^\top \mathbf{c}.$$

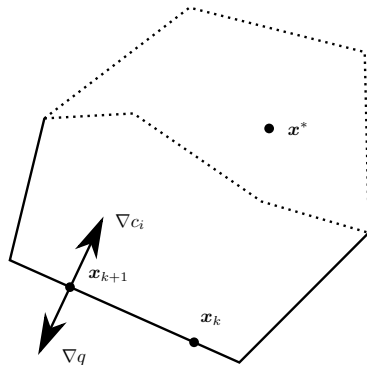
Consequences:

- ▶ equality-constrained problems can be converted into unconstrained ones
- ▶ inequality-constrained problems can be converted into equality-constrained ones (\hookrightarrow active set method)

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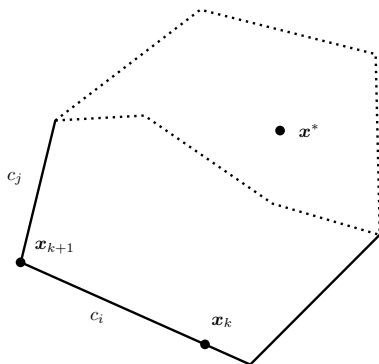
Active set method:

1. start with feasible point
2. solve problem in subset spanned by relevant constraints (*working set*)
3. if no blocking encountered, check KKT condition: terminate or deactivate constraint and go to 2.



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- else add blocking constraint to working set
- continue with 2.



Exercises

1. Consider the linear mapping $f : \mathbb{R}^3 \mapsto \mathbb{R}^2$ given by the matrix

$$\mathbf{A} = \begin{pmatrix} 1 & 3 & 1 \\ 1 & 1 & 2 \end{pmatrix}.$$

Find a basis of the null space $\ker \mathbf{A}$.

Exercises

2. Minimize $q : \mathbb{R}^2 \mapsto \mathbb{R}$,

$$q(x_1, x_2) = x_1^2 + 2x_2^2 + 2x_1x_2,$$

subject to the constraint

$$x_1 + 3x_2 = 2$$

by the null space method. Compare the result to the one obtained using the constraint to eliminate x_1 from $q(x_1, x_2)$.